Your Specifications for **Robo-navi-Smart**

Date: /   /

Thank you for your inquiry about **Robo-navi-Smart**. Please fill in and send us back.

1 ）Trading Company		
Company name		
Department		Position
Name		

2 ）Manufacturer		
Company name		
Department		Position
Name		

3) Power supply frequency — ☐ 50Hz   ☐ 60Hz

4) Your spot welding machine — Maker （   ）

5) Squeeze time ——————（   cycle ）

6) Nut feeding method ———— ☐ Feeder ☐ Manual feed

7) Nut feeder ———————— Maker （   ）

8) Air piping ——————— from the primary side

> ⚠
> **· Use a dedicated guide pin.**
> · Set the start-up self-hold on the welding machine to activate when the current starts to flow.
> · Upper tip needs clearance for guide pin.
> · Please provide us 5 pcs. each of nut samples.

9) Specification

Nut size	Nut shape			Hole diameter of work	Board thickness	Welding current	Weld flow time
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle

10) Type of Robo-navi-Smart

☐ Robot-Benri Holder Type   ☐ Platen Type

Example

Your Specifications for Robo-navi-Smart

Date:　/　/

Thank you for your inquiry about **Robo-navi-Smart**. Please fill in and send us back.

1) Trading Company				2) Manufacturer			
Company name	Trading Company name			Company name	Manufacturer Company name		
Depart-ment	sales department	Position	General Manager	Depart-ment	sales department	Position	General Manager
Name	John Doe			Name	Jane Doe		

3) Power supply frequency — ☑ 50Hz　☐ 60Hz

4) Your spot welding machine — Maker （ Maker name ）

5) Squeeze time ──────── (20 cycle)

6) Nut feeding method ──── ☑ Feeder ☐ Manual feed

7) Nut feeder ───────── Maker （ Maker name ）

8) Air piping ───────── from the primary side

⚠

· **Use a dedicated guide pin.**

· Set the start-up self-hold on the welding machine to activate when the current starts to flow.

· Upper tip needs clearance for guide pin.

· Please provide us 5 pcs. each of nut samples.

9) Specification

Nut size	Nut shape			Hole diameter of work	Board thickness	Welding current	Weld flow time
M 6	☑ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ 7	t 1.6	11,000 A	6 cycle
M 8	☑ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ 9	t 1.2	12,000 A	8 cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle
M	☐ Square ☐ Hex ☐ Round ☐ Flange type ☐ T-nut ☐ Hex cap nut ☐ Other ( )			φ	t	A	cycle

10) Type of Robo-navi-Smart

☑ Robot-Benri Holder Type　　☐ Platen Type

SMK

SMK